



Extra information for ... Max actuators - size M

for optimization of planning, installation and initial startup for safe operation



Assembly

-) Dimensions, drill plate
- Control elements: switch -push buttons -LED
-) Outdoor installation
- Mounting on air dampers(form-fit)
- Mounting on fire dampers(form-fit)
-) Mounting on butterfly valvesand ball valves
- Mounting of terminal box ...Boxand auxiliary switch ... Switch

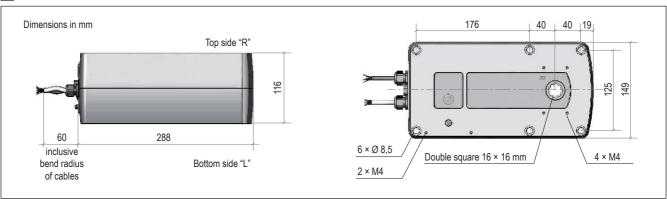


Flectric

- Power supply design
- Line cross sections
- Problem treatment/error indication

Subject to change!

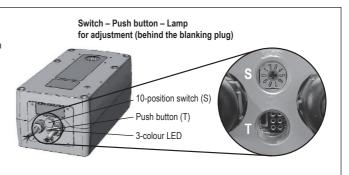
Dimensions



★ Control elements: switch – push button – LED

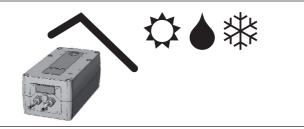
All actuators are equipped with a 10-position switch, a push button and a multicolour LEDfor calibration. Thesecontrol elements are to be found cable-laterally behind the two middle sectioned dummy plugs. For operation these must be removed. The calibration can be achieved despite lining up power supply at the actuator. The explosion prevention is not impaired thereby. However, it has to be of great concern that the dummy plugs must be rescrewed in order to comply with the IP-protection class.

The operation of the switch and button has to be done by means of a small screwdriver. Forcewith strong pressure and/or rotation is to be avoided in any case, since otherwise control electronics can be damaged irreparably. Adjustments of torque and running time can be achieved also before mounting. The adjustment of angle of rotation can be started only with an outside load and accurate mounting.



When mounting actuator outdoors it has to be certain that the actuator is protected against direct sun exposure (heat and UVI), rain and snow by employing an enclosure roof. Supply voltage is to be applied immediately after mounting in order to assure integrated heating at start.

Since actuators must have an internal temperature fuse, they may not be exposed to a too high temperature, neither at storage nor during operation. Otherwise the fuse could respond and switch off the actuator irreversibly.







Mounting of ... Max actuators

...Max actuators sizeM are equipped with a 16! 16 mm (double square)shaft connection by default. The form-fitting shaft connection is the most secure connection between damper shaft and actuator because slipping or slipping through is avoided compared to the force-fit clamp-connection.

The actuator will be connected firmly to the damper or fixed to a mounting bracket by means of four screws M8 (scope of delivery).

For square damper shafts 12 $!\,$ 12 mm or 14 $!\,$ 14 mm reducing bushes are also available.

The actuators are axially symmetric developed. In case of spring return function the safety position must be selected by turning the actuator to 180° .

Furthermore it is to be considered that the actuators have a total angle movement of approx. 95° in order to realize a pretension on the control element (damper or the like). Therefore the actuator sits tilted on the damper shaft.

In order to adjust this and to induce pretension, the driving shaft has to be alined mechanically over the hand-operated control socket "HV" when connecting to the damper shaft.

The socket wrench has to be turned counterclockwise when facing the actuator's "side R", facing "side L" turn manual override clockwise.

Attention: Mount with appropriate safety precautions only!

- The drive shaft may only be mechanically adjusted either with the provided socket wrench or the optional accessory "HV-MK" manual override (turn off power supply). External force applied to the shaft can lead to mechanical damage of the actuator!
- At the manual override counteracting forces occur when mounting spring return actuators. Do NOTrelease manual override under spring tension!
- · Pressthe "T" (push button) for 3 secondsafter installation.
- To ensure the calibration of the positioning angle, The T-push button should be pressed once every 6 months.

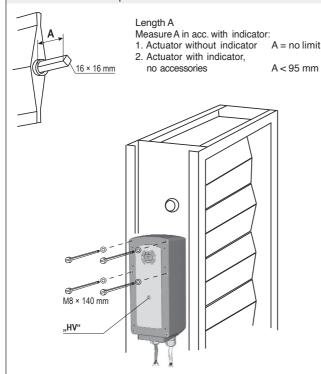
Mounting on air dampers

Form-fitted shaft connection - Mounting on square damper shaft

Mounting:

- Affix tap holes M8 (in accordancewith drill template) on the damper or to a mounting bracket.
- Adjust drive shaft of the actuator with the socketwrench that the drive stands perpendicularly to the damper before plugging actuator onto the damper shaft.
- 3. Plug actuator onto damper shaft and fix diagonally with 2 screws.
- 4. Remove the socket wrench.
- 5. Pivot and tighten the remaining screws.

Dimension of the damper shaft





4 screws M8! 140 mm as well as a socket wrench are part of delivery. For square damper shafts 12! 12 mm or 14! 14 mm reducing bushes are available as optional accessories.



Mounting on fire dampers

ExMax-...-BFand RedMax-...-BFactuators integrate an intrinsically safe circuit in order to connect an ExPro-TT-...sensor which works like a temperature trigger. InMax-... and InPro-TT-... are for non hazardous areas.

Mounting:

- 1. Affix tap holes M8 (in accordancewith drill template) on the damper or to a mounting bracket
- 2. Adjust drive shaft of the actuator with the socketwrench that the drive stands perpendicularly to the damper before plugging actuator onto the damper shaft
- 3. Plug actuator onto damper shaft and fix diagonally with 2 screws
- 4. Remove the socket wrench
- 5. Pivot and tighten the remaining screws

- Mount temperature trigger ...Pro-TT-...
 Mount terminal box (type ...Box-BF)
 Plug sensor connector into actuator's socket

Connection of safety temperature trigger ...Pro-TT-...







The temperature trigger is mounted directly to the duct or damper wall with pre-assembled tapping screws. The position of the safety elements must guarantee free air flow.

...Pro-TT-...is mounted to the actuator by means of quick fastener M12.

Mounting to ball valves and butterfly valves

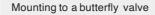
Actuators of sizeM are equipped by default with a 16! 16 mm double squareform-fitting shaft connection. For mounting to butterfly valves or ball valves a special mounting bracket in acc. with DIN ENISO5211 is required.

Since this standard provides only certain basic conditions there can be substantial geometrical differences between armatures which require a special adaption.

Mounting to a ball valve







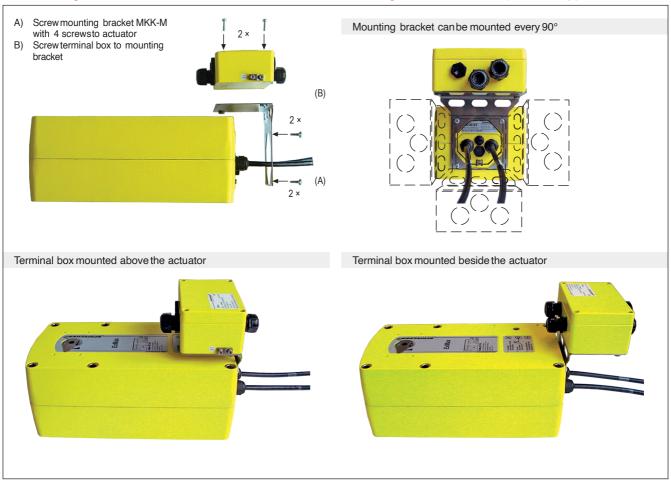




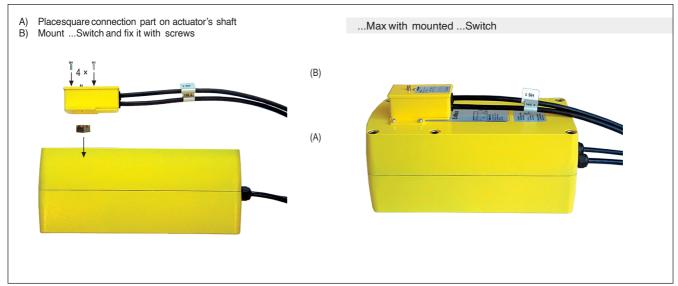




Mounting of terminal boxes ... Box to actuator via mounting bracket MKK-M (accessory)



Mounting of auxiliary switch ... Switch to actuator





Inrush current and electrical fuse

The inrush current can vary in the microsecond range depending on the random phase on the sinusoidal voltage of the power supply.

Eachactuator shall be protected with a single type D/2A miniature circuit breaker when operating at 240VAC.

In casethat the electrical protection with single circuit breaker is not desired or possible, appropriate professional measures shall be taken by the installers.

Suggestions for possible actions are listed below. This list does not claim to be exhaustive:

- · Connecting appropriate resistors and/or chokes (ferrites) ahead of the actuators
- · Time-delayed switching of the actuators to the supply voltage

The appropriate designing and installation shall be the responsibility of the commissioning engineer.

Power input depending on supply voltage

The design of the on-site supply depends on the selected motor running time and selected supply voltage. Accompanying values are "about values" since there can be construction unit dispersions within electronics. The holding power is run time independently typical at ~ 5 W. The power consumption for the heater is ~ 16 W. In the heating phase the motor is not active!

The power supply unit needs about 1 second to initiallize the actuator motor-starting current 2.0 A. (please consider this while concepting the cross section of the supply line). The power factor is between 0.8 and 0.5 in dependence of motor running time.

		Rated current in acc. with motor running time						
Voltage	Current	40 s	60 s	90 s	120 s	150 s		
24 V DC	Nominal	1,5 A	1,0 A	0,8 A	0,7 A	0,7 A		
120 V AC	Nominal	0,26 A	0,18 A	0,14 A	0,12 A	0,12 A		
240 V AC	Nominal	0,13 A	0,09 A	0,07 A	0,06 A	0,06 A		

✓ LEDfunction

LED Status		Slot (100msfor each slot)								
	1	2	3	4	5	6	7	8	9	10
Electronics not supplied with voltage / Electronics defective (call service)										
Initialization of actuator (electronic start up) if status not changed after 10s: failure call service										
Internal failure call service/ blockage										
Internal failure call service/ blockage										
Saveof parameters from US-Stickcomplete										
Fire safe not connected/ broken (BF-actuators)										
Endposition "open"										
Endposition "closed"										
Self-adjustment run										
Normal operation mode										
Self-adjustment run (y-actuator used as a 3P-version)										
Normal operation mode (y-actuator used as a 3P-version)										

All other features of the actuators are not affected.





Problem handling / Error indication

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